Probabilistic Models

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Machine Learning

Outline

1. **Probabilistic Models**
2. **Maximum Likelihood Estimation**
   - Linear Regression
   - Logistic Regression
3. **Maximum A Posteriori Estimation**
4. **Bayesian Estimation and Inference***
   - Gaussian Process

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Predictions based on Probability

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- How to find Θ?

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- After being solved, $\Theta_{\text{ML/MAP}}$ is treated as a constant when make a prediction $\hat{\boldsymbol{y}} = \arg\max_{\boldsymbol{y}} \mathrm{P}(\boldsymbol{y} \mid \boldsymbol{x}; \Theta_{\text{ML/MAP}})$

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- ML estimation for $\boldsymbol{w}^*$:

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Probabilistic Models for Binary Classification

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- ML estimate $\mathrm{P}(\mathbb{X} \,|\, \rho)$? How to relate $\boldsymbol{x}$ to ρ?

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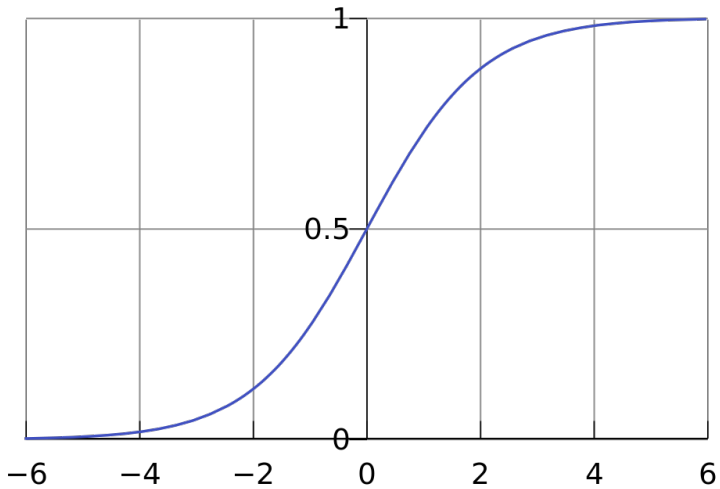

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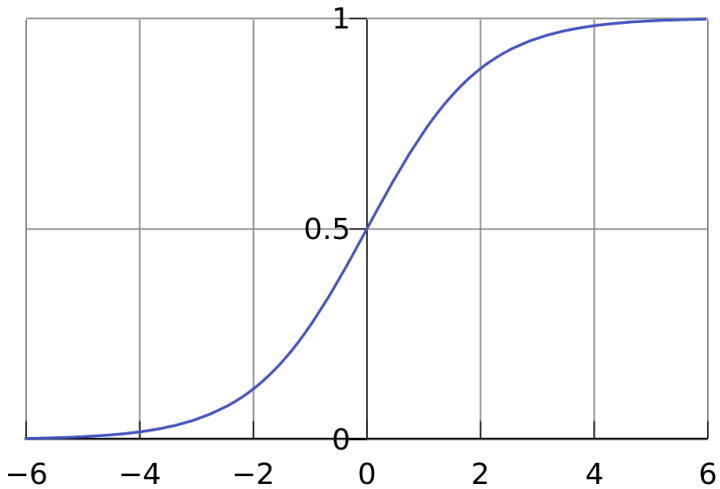

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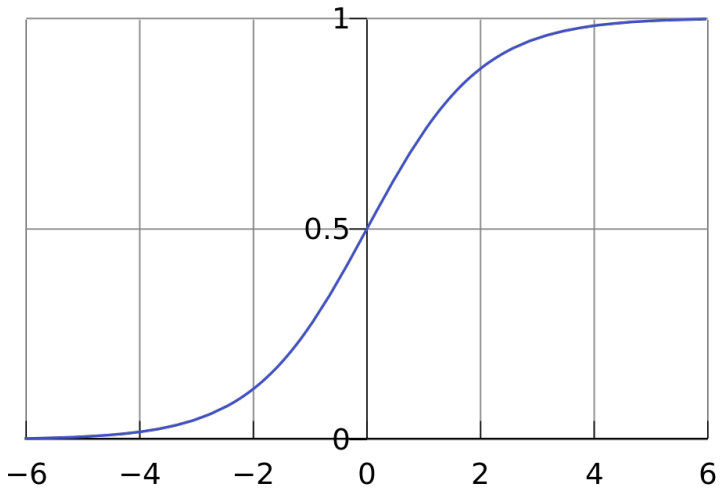

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Logistic Regression

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- How to learn $\boldsymbol{w}$ from $\mathbb{X}$?
- ML estimation:

$$\boldsymbol{w}_{\mathrm{ML}} = \arg\max_{\boldsymbol{w}} \mathrm{P}(\mathbb{X} \,|\, \boldsymbol{w})$$

ML Estimation

- Log-likelihood:

$$\begin{aligned}\log \mathrm{P}(\mathbb{X} \,|\, \boldsymbol{w}) &= \log \textstyle\prod_{i=1}^{N} \mathrm{P}\left(\boldsymbol{x}^{(i)}, y^{(i)} \,|\, \boldsymbol{w}\right) \\ &= \log \textstyle\prod_{i} \mathrm{P}\left(y^{(i)} \,|\, \boldsymbol{x}^{(i)}, \boldsymbol{w}\right) \mathrm{P}\left(\boldsymbol{x}^{(i)} \,|\, \boldsymbol{w}\right)\end{aligned}$$

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&= \textstyle\sum_i y'^{(i)} \boldsymbol{w}^\top \boldsymbol{x}^{(i)} - \log(1 + e^{\boldsymbol{w}^\top \boldsymbol{x}^{(i)}}) \text{ [Homework]}
\end{aligned}$$

- Unlike in linear regression, we cannot solve $\boldsymbol{w}$ analytically in a closed form via

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- But since $\log \mathrm{P}(\mathbb{X}|\boldsymbol{w})$ is differentiable w.r.t. $\boldsymbol{w}$, we can solve $\boldsymbol{w}^*_{\mathrm{ML}}$ numerically using stochastic gradient descent (SGD)
  - It can be shown that $\log \mathrm{P}(\mathbb{X}|\boldsymbol{w})$ is concave in terms of $\boldsymbol{w}$ [1]
  - SGD finds global optimal

Outline

MAP Estimation

- So far, we solve $\boldsymbol{w}$ by ML estimation:

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- In MAP estimation, we solve

$$\boldsymbol{w}_{\text{MAP}} = \arg\max_{\boldsymbol{w}} \text{P}(\boldsymbol{w} \,|\, \mathbb{X}) = \arg\max_{\boldsymbol{w}} \text{P}(\mathbb{X} \,|\, \boldsymbol{w}) \text{P}(\boldsymbol{w})$$

- $\text{P}(\boldsymbol{w})$ models our ***preference*** or ***prior knowledge*** about $\boldsymbol{w}$

MAP Estimation for Linear Regression

- MAP estimation in linear regression:

$$\boldsymbol{w}_{\text{MAP}} = \arg\max_{\boldsymbol{w}} \log[\text{P}(\mathbb{X}\,|\,\boldsymbol{w})\text{P}(\boldsymbol{w})]$$

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$$\log[\text{P}(\mathbb{X}|\boldsymbol{w})\text{P}(\boldsymbol{w})] = \log \text{P}(\mathbb{X}|\boldsymbol{w}) + \log \text{P}(\boldsymbol{w}) \propto -\sum_i \left(y^{(i)} - \boldsymbol{w}^\top \boldsymbol{x}^{(i)}\right)^2$$
$$+ \log \sqrt{\frac{1}{(2\pi)^D \det(\beta^{-1}\boldsymbol{I})}} \exp\left[-\frac{1}{2}(\boldsymbol{w}-\boldsymbol{0})^\top (\beta^{-1}\boldsymbol{I})^{-1}(\boldsymbol{w}-\boldsymbol{0})\right]$$

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- $\mathrm{P}(\boldsymbol{w})$ corresponds to the ***weight decay*** term in Ridge regression
- MAP estimation provides a way to design complicated yet interpretable regularization terms
  - E.g., we have LASSO by letting $\mathrm{P}(\boldsymbol{w}) \sim \text{Laplace}(0, b)$ [Proof]
  - We can also let $\mathrm{P}(\boldsymbol{w})$ be a mixture of Gaussians

Remarks on ML and MAP Estimation

Theorem (Consistency)

The ML estimator Θ_{ML} *is* ***consistent****, i.e.,* $\lim_{N\to\infty}\Theta_{ML} \xrightarrow{\Pr} \Theta^*$ *as long as the "true"* $\mathrm{P}(y\,|\,\boldsymbol{x};\Theta^*)$ *lies within our model* $\mathbb{F}$*.*

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Theorem (Cramér-Rao Lower Bound [2])

At a fixed (large) number N of examples, no consistent estimator of $\hat{\Theta}$ has a lower expected MSE (mean square error) than the ML estimator Θ_{ML}.

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Outline

Bayesian Estimation

- In ML/MAP estimation, we use the estimated $\hat{\Theta}$ as a constant to make prediction:

$$\hat{\boldsymbol{y}} = \arg\max_{\boldsymbol{y}} \mathrm{P}(\boldsymbol{y} \,|\, \boldsymbol{x}; \hat{\Theta})$$

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  - $\hat{\Theta} = \arg\max_{\Theta} \mathrm{P}(\Theta \,|\, \mathbb{X})$
- ***Bayesian inference*** threats Θ as a random variable when making prediction:

$$\mathrm{P}(\boldsymbol{y} \,|\, \boldsymbol{x}, \mathbb{X}) = \int_{\Theta} \mathrm{P}(\boldsymbol{y}, \Theta \,|\, \boldsymbol{x}, \mathbb{X}) d\Theta = \int \mathrm{P}(\boldsymbol{y} \,|\, \boldsymbol{x}, \Theta) \mathrm{P}(\Theta \,|\, \mathbb{X}) d\Theta$$

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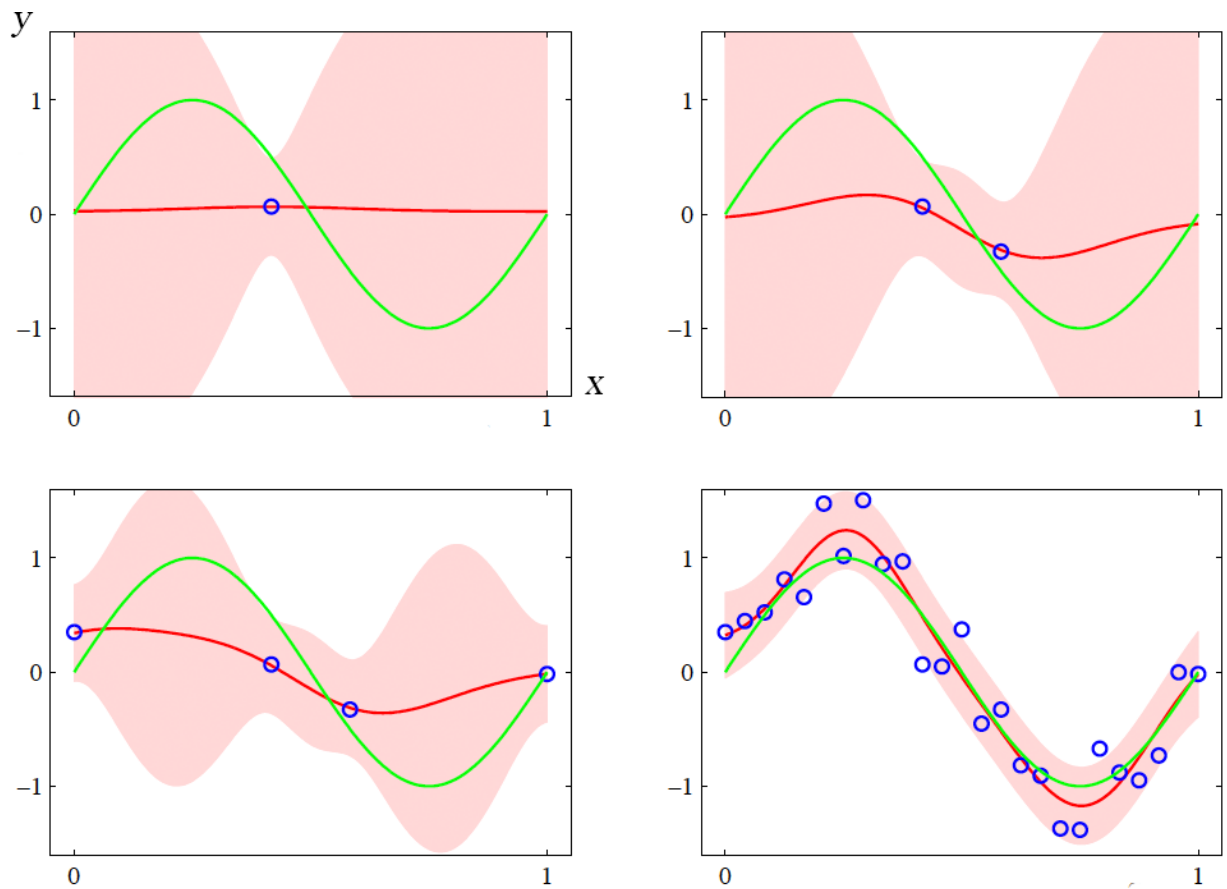
  - **Entire distribution** $\mathrm{P}(\boldsymbol{y} \,|\, \boldsymbol{x}, \mathbb{X})$ is calculated, so we get not only $\hat{\boldsymbol{y}} = \arg\max_{\boldsymbol{y}} \mathrm{P}(\boldsymbol{y} \,|\, \boldsymbol{x}, \mathbb{X})$ but the uncertainty of each prediction
  - ***Bayesian estimation of Θ:*** each prediction considers ***all*** Θ's (weighted by their chances $\mathrm{P}(\Theta \,|\, \mathbb{X})$)

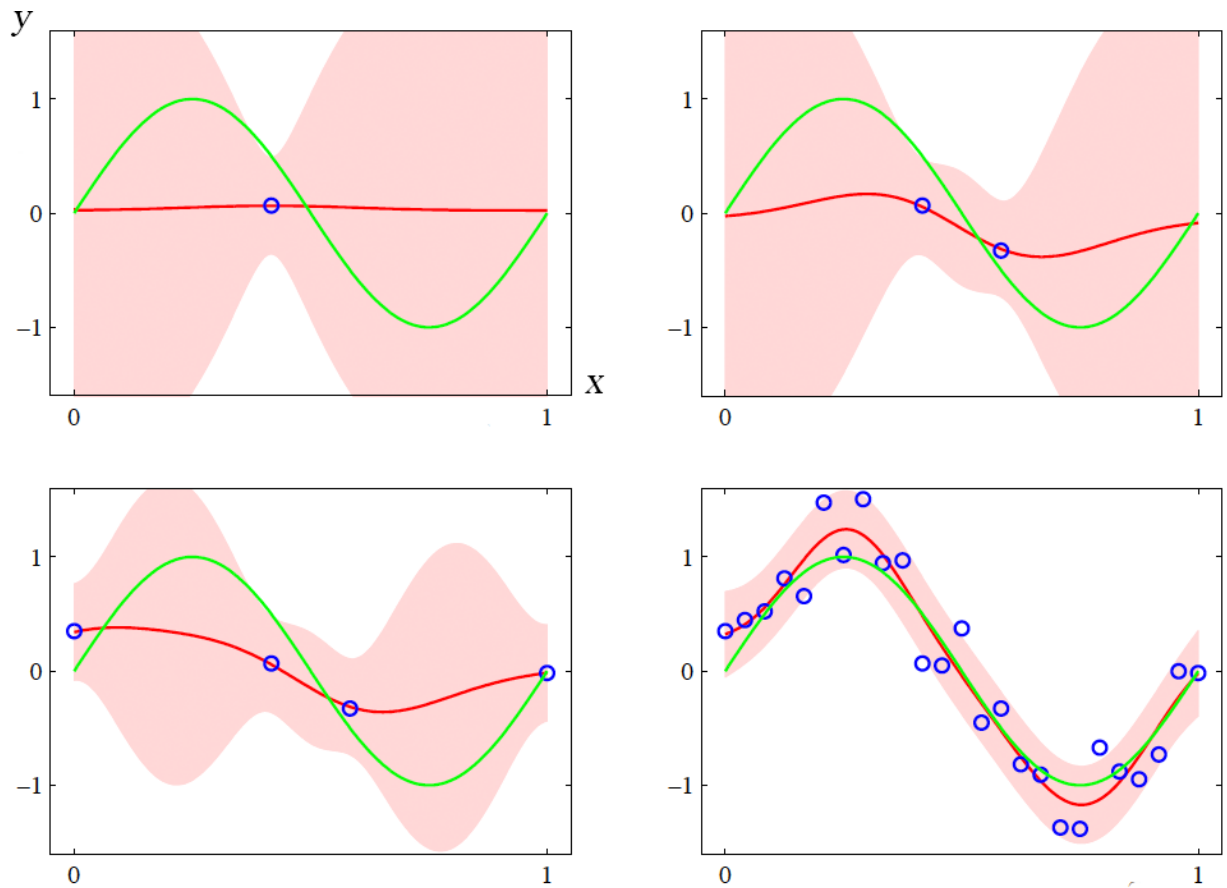
Example: 1D Regression

- Let $\mathrm{y} = f^*(\mathrm{x}) + \varepsilon$
  - Green line: $f^*(\cdot)$
  - Blue dots: noisy examples



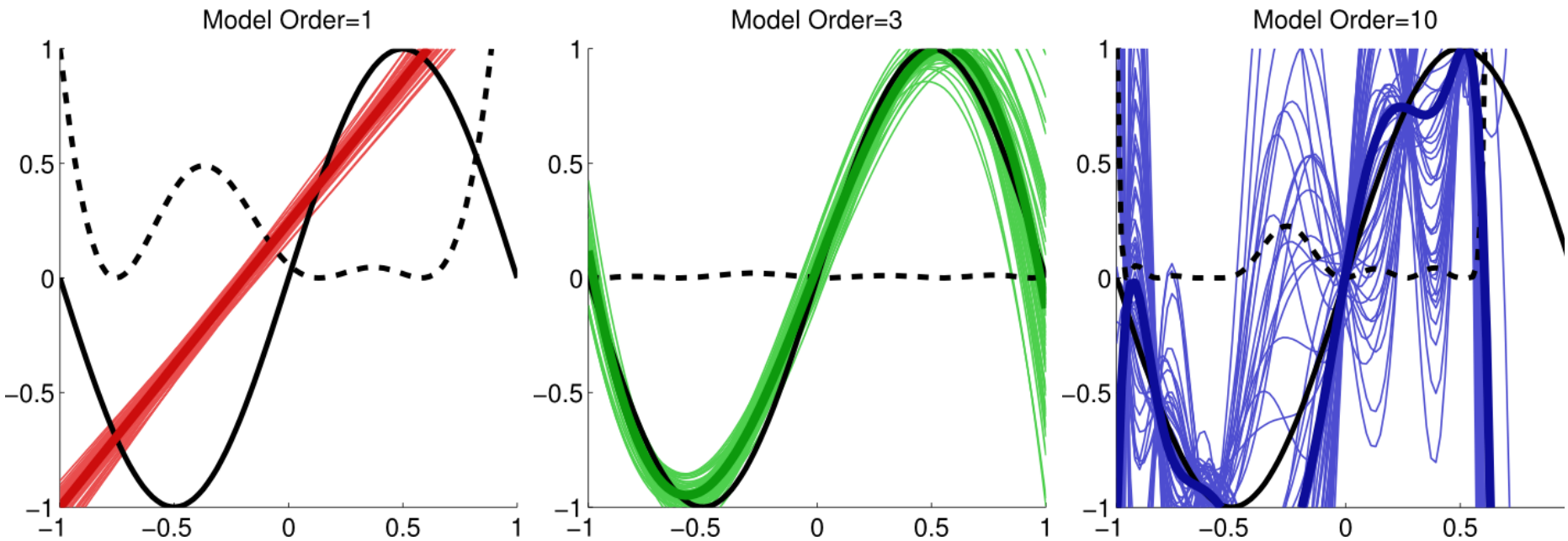
Example: 1D Regression

- Let $\mathrm{y} = f^*(\mathrm{x}) + \varepsilon$
  - Green line: $f^*(\cdot)$
  - Blue dots: noisy examples
- Red line: predictions by a Bayesian regressor (Gaussian Process)
- Shaded area: confidence intervals of predictions



Bayesian vs. ML Estimation

- Recall the bias-variance trade-off an ML-base polynomial regressor:



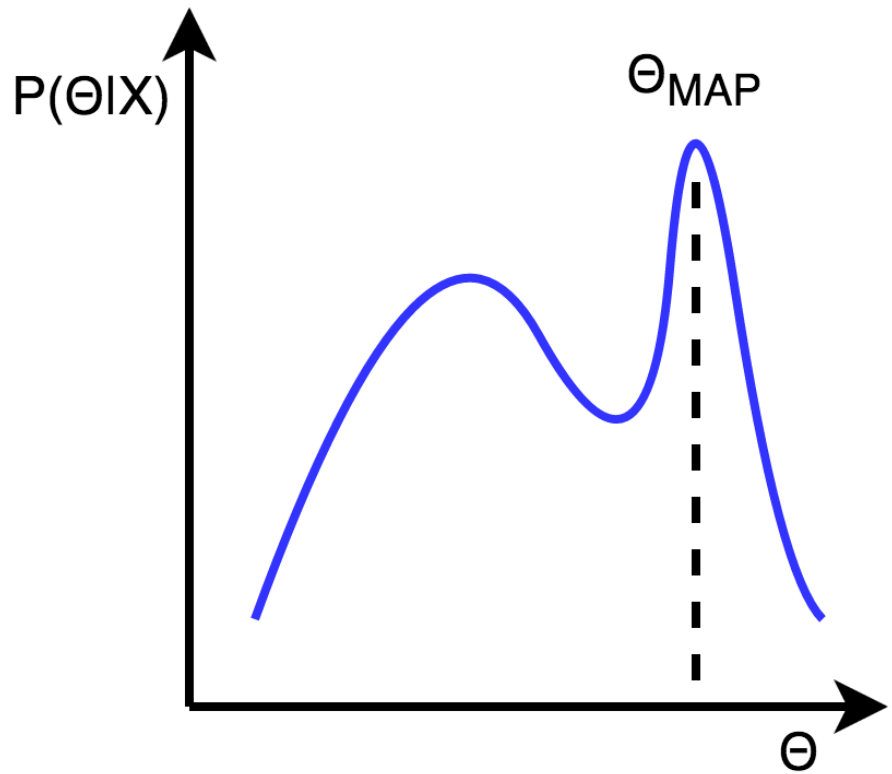
- Bayesian regressor usually generalizes better when the size N of training set is small
  - Avoids high variance $\mathrm{Var}_{\mathbb{X}}(\Theta_{\mathrm{ML}})$

Bayesian vs. MAP Estimation

- MAP gains some benefit of Bayesian approach by incorporating prior as $\text{bias}(\Theta_{\text{MAP}})$
  - Reduces $\text{Var}_{\mathbb{X}}(\Theta_{\text{MAP}})$ when training set is small

Bayesian vs. MAP Estimation

- MAP gains some benefit of Bayesian approach by incorporating prior as $\text{bias}(\Theta_{\text{MAP}})$
  - Reduces $\text{Var}_{\mathbb{X}}(\Theta_{\text{MAP}})$ when training set is small
- However, does ***not*** work if Θ_{MAP} is unrepresentative of the majority Θ in $\int \text{P}(\boldsymbol{y}, \Theta | \boldsymbol{x}, \mathbb{X}) d\Theta = \int \text{P}(\boldsymbol{y} | \boldsymbol{x}, \Theta) \text{P}(\Theta | \mathbb{X}) d\Theta$
- E.g. when $\text{P}(\Theta | \mathbb{X})$ is a mixture of Gaussian



Evaluating $\mathrm{P}(\boldsymbol{y}\,|\,\boldsymbol{x}, \mathbb{X})$

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- Integral computation make the evaluation challenging
  - The solution may not be tractable in many applications

Evaluating $\mathrm{P}(\boldsymbol{y} \mid \boldsymbol{x}, \mathbb{X})$

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- Integral computation make the evaluation challenging
  - The solution may not be tractable in many applications
- Fortunately, in the context of Bayesian linear regression, $\mathrm{P}(\boldsymbol{y} \mid \boldsymbol{x}, \mathbb{X})$ can have a simple, closed form [3]

Bayesian Linear Regression

- Assuming that $y = \boldsymbol{w}^\top \mathbf{x} + \varepsilon$, where $\varepsilon \sim \mathcal{N}(0, \sigma_\varepsilon)$, we have

$$\begin{aligned} \mathrm{P}(y|\boldsymbol{x}, \mathbb{X}) &= \int_{\boldsymbol{w}} \mathrm{P}(y, \boldsymbol{w}|\boldsymbol{x}, \mathbb{X}) d\boldsymbol{w} = \int \mathrm{P}(y|\boldsymbol{x}, \boldsymbol{w}) \mathrm{P}(\boldsymbol{w}|\mathbb{X}) d\boldsymbol{w} \\ &= \frac{1}{\mathrm{P}(\mathbb{X})} \int \mathrm{P}(y|\boldsymbol{x}, \boldsymbol{w}) \mathrm{P}(\mathbb{X}|\boldsymbol{w}) \mathrm{P}(\boldsymbol{w}) d\boldsymbol{w} \\ &= \frac{\Pi_{i=1}^{N} \mathrm{P}(\boldsymbol{x}^{(i)})}{\mathrm{P}(\mathbb{X})} \int \mathrm{P}(y|\boldsymbol{x}, \boldsymbol{w}) \Pi_{i=1}^{N} \mathrm{P}(y^{(i)}|\boldsymbol{x}^{(i)}, \boldsymbol{w}) \mathrm{P}(\boldsymbol{w}) d\boldsymbol{w} \end{aligned}$$

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- $\mathrm{P}(y|\boldsymbol{x}, \boldsymbol{w}) \sim \mathcal{N}(\boldsymbol{w}^\top \boldsymbol{x}, \sigma_\varepsilon)$ and $\mathrm{P}(y^{(i)}|\boldsymbol{x}^{(i)}, \boldsymbol{w}) \sim \mathcal{N}(\boldsymbol{w}^\top \boldsymbol{x}^{(i)}, \sigma_\varepsilon)$, $\forall i$

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- If we assume that $\boldsymbol{w} \sim \mathcal{N}$, then $\mathrm{P}(y|\boldsymbol{x}, \boldsymbol{w}) \Pi_i \mathrm{P}(y^{(i)}|\boldsymbol{x}^{(i)}, \boldsymbol{w}) \mathrm{P}(\boldsymbol{w})$ can be described by an $N+2$ dimensional Gaussian
  - $(y|\boldsymbol{x}, \boldsymbol{w})$, $(y^{(i)}|\boldsymbol{x}^{(i)}, \boldsymbol{w})$, and $\boldsymbol{w}$ are (conditionally) independent with each other

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  - $(y|\boldsymbol{x}, \boldsymbol{w})$, $(y^{(i)}|\boldsymbol{x}^{(i)}, \boldsymbol{w})$, and $\boldsymbol{w}$ are (conditionally) independent with each other
- Its marginalization, $\mathrm{P}(y|\boldsymbol{x}, \mathbb{X}) = \int \mathrm{P}(y, \boldsymbol{w}|\boldsymbol{x}, \mathbb{X}) d\boldsymbol{w}$ is also a Gaussian
  - Gaussian distribution is closed under marginalization

Bayesian Linear Regression

- Assuming that $y = \boldsymbol{w}^\top \mathbf{x} + \varepsilon$, where $\varepsilon \sim \mathcal{N}(0, \sigma_\varepsilon)$, we have

$$\begin{aligned} \mathrm{P}(y|\boldsymbol{x}, \mathbb{X}) &= \int_{\boldsymbol{w}} \mathrm{P}(y, \boldsymbol{w}|\boldsymbol{x}, \mathbb{X}) d\boldsymbol{w} = \int \mathrm{P}(y|\boldsymbol{x}, \boldsymbol{w}) \mathrm{P}(\boldsymbol{w}|\mathbb{X}) d\boldsymbol{w} \\ &= \frac{1}{\mathrm{P}(\mathbb{X})} \int \mathrm{P}(y|\boldsymbol{x}, \boldsymbol{w}) \mathrm{P}(\mathbb{X}|\boldsymbol{w}) \mathrm{P}(\boldsymbol{w}) d\boldsymbol{w} \\ &= \frac{\Pi_{i=1}^N \mathrm{P}(\boldsymbol{x}^{(i)})}{\mathrm{P}(\mathbb{X})} \int \mathrm{P}(y|\boldsymbol{x}, \boldsymbol{w}) \Pi_{i=1}^N \mathrm{P}(y^{(i)}|\boldsymbol{x}^{(i)}, \boldsymbol{w}) \mathrm{P}(\boldsymbol{w}) d\boldsymbol{w} \end{aligned}$$

- $\mathrm{P}(y|\boldsymbol{x}, \boldsymbol{w}) \sim \mathcal{N}(\boldsymbol{w}^\top \boldsymbol{x}, \sigma_\varepsilon)$ and $\mathrm{P}(y^{(i)}|\boldsymbol{x}^{(i)}, \boldsymbol{w}) \sim \mathcal{N}(\boldsymbol{w}^\top \boldsymbol{x}^{(i)}, \sigma_\varepsilon)$, $\forall i$
- If we assume that $\boldsymbol{w} \sim \mathcal{N}$, then $\mathrm{P}(y|\boldsymbol{x}, \boldsymbol{w}) \Pi_i \mathrm{P}(y^{(i)}|\boldsymbol{x}^{(i)}, \boldsymbol{w}) \mathrm{P}(\boldsymbol{w})$ can be described by an $N+2$ dimensional Gaussian
  - $(y|\boldsymbol{x}, \boldsymbol{w})$, $(y^{(i)}|\boldsymbol{x}^{(i)}, \boldsymbol{w})$, and $\boldsymbol{w}$ are (conditionally) independent with each other
- Its marginalization, $\mathrm{P}(y|\boldsymbol{x}, \mathbb{X}) = \int \mathrm{P}(y, \boldsymbol{w}|\boldsymbol{x}, \mathbb{X}) d\boldsymbol{w}$ is also a Gaussian
  - Gaussian distribution is closed under marginalization
- Why not model $(y|\boldsymbol{x}, \mathbb{X}) \sim \mathcal{N}$ in the first place?

Outline

Gaussian Process

- Assume a model $\mathbb{F}$ where the domain of each $f(\cdot) \in \mathbb{F}$ consists of only N inputs $\boldsymbol{x}^{(1)}, \cdots, \boldsymbol{x}^{(N)}$
- Let $y^{(i)} = f(\boldsymbol{x}^{(i)}) \in \mathbb{R}$, $\forall i$, we can compactly represent $f(\cdot)$ as a vector $\boldsymbol{y} = [y^{(1)}, \cdots, y^{(N)}]^\top$
- We can specify the probability of $f(\cdot)$ by assuming a distribution over $\boldsymbol{y}$, e.g., $\boldsymbol{y} \sim \mathcal{N}(\boldsymbol{\mu}, \Sigma)$

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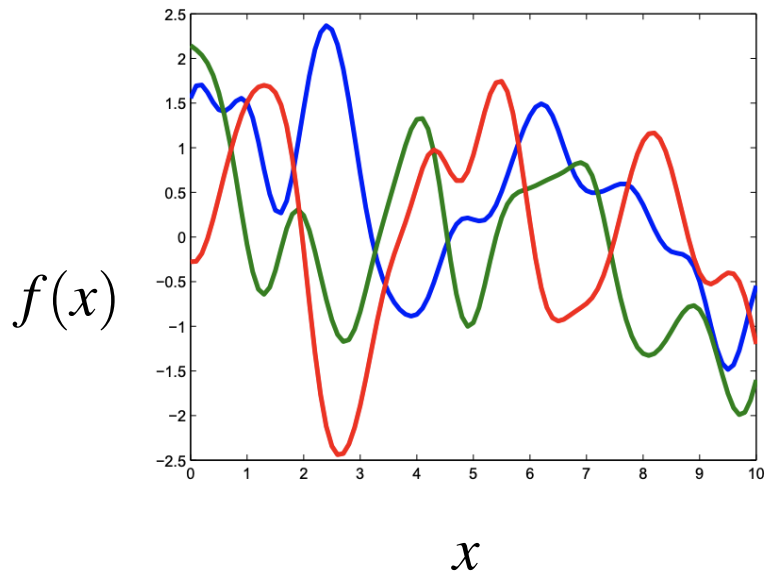
- We can specify the probability of $f(\cdot)$ by assuming a distribution over $\boldsymbol{y}$, e.g., $\boldsymbol{y} \sim \mathcal{N}(\boldsymbol{\mu}, \Sigma)$
- A ***stochastic process*** is a random distribution over functions in $\mathbb{F}$
  - Alternatively, it can be a set of random random variables $\{\boldsymbol{y}^{(i)} \equiv f(\boldsymbol{x}^{(i)})\}_i$ indexed by time or space i



Gaussian Process (GP)

- A ***Gaussian process*** is a stochastic process of which the distribution is defined by a mean function $m(\cdot)$ and covariance/***kernel*** function $k(\cdot,\cdot)$:

$$\begin{bmatrix} y^{(1)} \\ \vdots \\ y^{(N)} \end{bmatrix} \sim \mathcal{N}(\boldsymbol{m} = \begin{bmatrix} m(\boldsymbol{x}^{(1)}) \\ \vdots \\ m(\boldsymbol{x}^{(N)}) \end{bmatrix}, \boldsymbol{K} = \begin{bmatrix} k(\boldsymbol{x}^{(1)},\boldsymbol{x}^{(1)}) & \cdots & k(\boldsymbol{x}^{(1)},\boldsymbol{x}^{(N)}) \\ \vdots & \ddots & \vdots \\ k(\boldsymbol{x}^{(N)},\boldsymbol{x}^{(1)}) & \cdots & k(\boldsymbol{x}^{(N)},\boldsymbol{x}^{(N)}) \end{bmatrix}$$

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- Intuition? If $\boldsymbol{x}^{(i)}$ and $\boldsymbol{x}^{(j)}$ are positively (or negatively) correlated, then $y^{(i)}$ and $y^{(j)}$ should be positively (or negatively) correlated too
- Common choices of mean and kernel functions:
  - $m(\cdot) = 0$
  - $k(\boldsymbol{x}^{(i)},\boldsymbol{x}^{(j)}) = \exp(-\frac{\|\boldsymbol{x}^{(i)}-\boldsymbol{x}^{(j)}\|^2}{2\tau^2})$ for some fixed $\tau \in \mathbb{R} - \{0\}$
- The kernel matrix $\boldsymbol{K}$ is usually made positive definite (when $\boldsymbol{x}^{(i)} \neq \boldsymbol{x}^{(j)}, \forall i,j$) so it is invertible

Bayesian Regression

- Given N examples $\mathbb{X} = \{(\boldsymbol{x}^{(i)}, y^{(i)})\}_{i=1}^{N}$, how to predict the labels of M unlabeled instances $\mathbb{X}' = \{\boldsymbol{x}'^{(i)}\}_{i=1}^{M}$?
- Gaussian process:

$$\begin{bmatrix} \boldsymbol{y}_N \\ \boldsymbol{y}_M \end{bmatrix} \sim \mathcal{N}\left(\begin{bmatrix} \boldsymbol{m}_N \\ \boldsymbol{m}_M \end{bmatrix}, \begin{bmatrix} \boldsymbol{K}_{N,N} & \boldsymbol{K}_{N,M} \\ \boldsymbol{K}_{M,N} & \boldsymbol{K}_{M,M} \end{bmatrix} \right),$$

  - $\boldsymbol{m}_N = \boldsymbol{m}_M = \boldsymbol{0}$ or $\bar{y}_N \boldsymbol{1}$, where $\bar{y}_N = \frac{1}{N}\Sigma_{i=1}^{N} y^{(i)}$
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- Bayesian inference:

$$\mathrm{P}(\boldsymbol{y}_M \,|\, \mathbb{X}', \mathbb{X}) = \mathcal{N}(\boldsymbol{K}_{M,N}\boldsymbol{K}_{N,N}^{-1}\boldsymbol{y}_N \,, \boldsymbol{K}_{M,M} - \boldsymbol{K}_{M,N}\boldsymbol{K}_{N,N}^{-1}\boldsymbol{K}_{N,M})$$

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  - Gaussian distribution is closed under conditioning
- There is ***no*** explicit training phase
- Predictions: $\hat{\boldsymbol{y}}_M = \boldsymbol{K}_{M,N}\boldsymbol{K}_{N,N}^{-1}\boldsymbol{y}_N$ (with uncertainty)

Noisy Data

- What if the examples $\mathbb{X} = \{(\boldsymbol{x}^{(i)}, y^{(i)})\}_{i=1}^{N}$ contain noise, i.e., $\mathrm{y} = f^*(\mathbf{x}) + \varepsilon$, $\varepsilon \sim \mathcal{N}(0, \sigma_\varepsilon^2)$?

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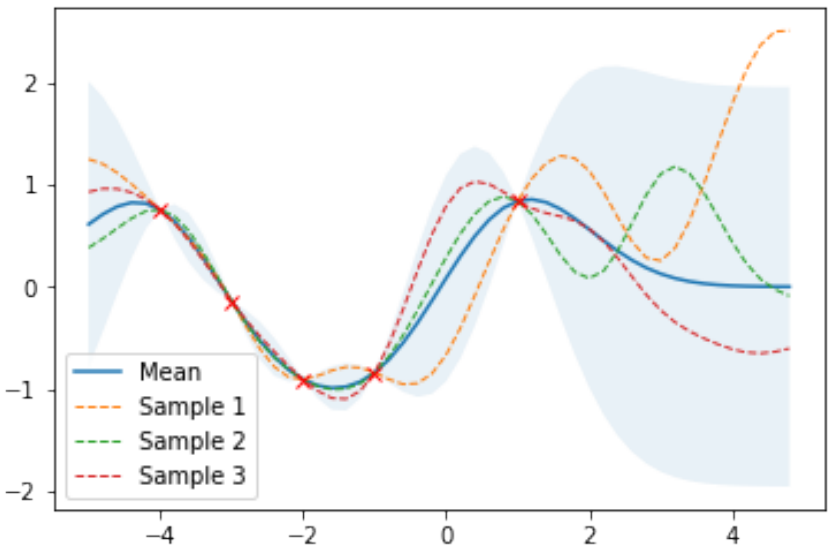
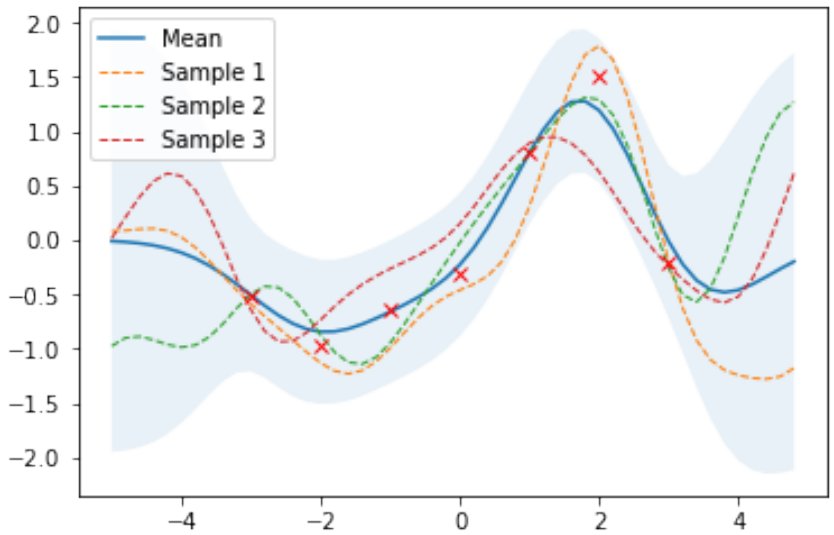
Predictions Given Clean and Noisy Data



Clean Data



Noisy Data

Other Choices of Kernels

- Radial basis function (RBF) or exponentiated quadratic kernel:

$$k(\boldsymbol{x}^{(i)}, \boldsymbol{x}^{(j)}) = \exp\left(-\frac{\|\boldsymbol{x}^{(i)} - \boldsymbol{x}^{(j)}\|^2}{2\tau^2}\right)$$

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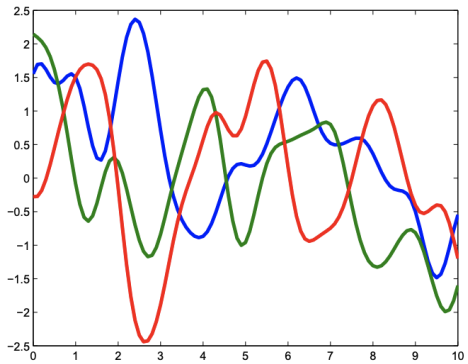
- Combined kernel:

$$k(\boldsymbol{x}^{(i)},\boldsymbol{x}^{(j)}) = k^{(1)}(\boldsymbol{x}^{(i)},\boldsymbol{x}^{(j)}) \cdot k^{(2)}(\boldsymbol{x}^{(i)},\boldsymbol{x}^{(j)}) \cdots$$

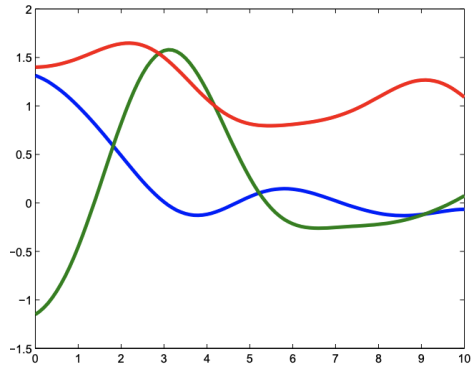
  - Has a high value only if all source covariances have a high value (AND operation)

Hyperparameter Tuning

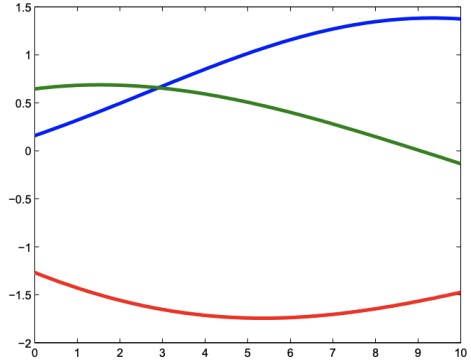
- The τ in the RBF kernel $k(\boldsymbol{x}^{(i)}, \boldsymbol{x}^{(j)}) = \exp(-\frac{\|\boldsymbol{x}^{(i)} - \boldsymbol{x}^{(j)}\|^2}{2\tau^2})$ controls the "smoothness" of the prediction functions



$\tau = 0.5$



$\tau = 2$



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  - More generally, how to decide the hyperparameters of chosen kernels?

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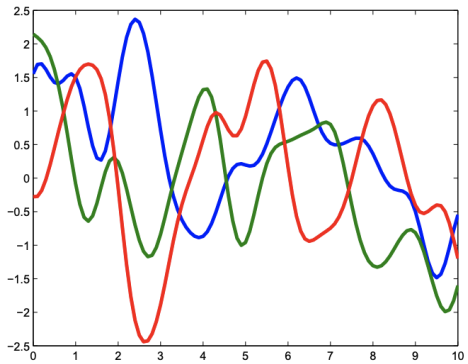

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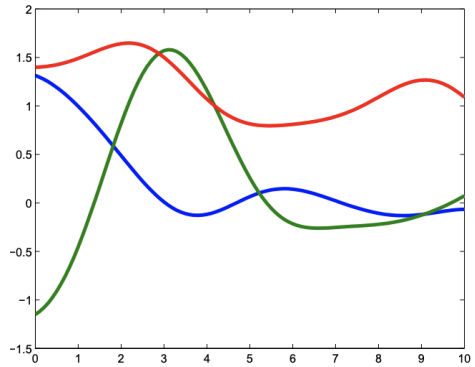

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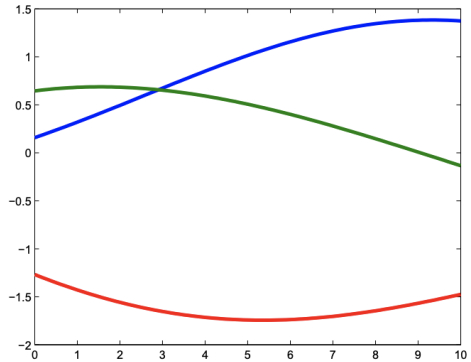

$\tau = 10$

- How to decide the best τ for a given $\mathbb{X}$?
  - More generally, how to decide the hyperparameters of chosen kernels?
- We can solve τ using the ML estimation we already familiar with:

$$\begin{aligned}\tau_{\text{ML}} &= \arg\min_\tau -\log \mathrm{P}(\mathbb{X}\,|\,\tau) = \arg\min_\tau -\log \mathrm{P}(\boldsymbol{y}_N\,|\,\boldsymbol{X}_N,\tau)\\ &= \arg\min_\tau (\boldsymbol{y}_N-\boldsymbol{m}_N)^\top \boldsymbol{K}_{N,N}^{-1}(\boldsymbol{y}_N-\boldsymbol{m}_N)+\log\det(\boldsymbol{K}_{N,N})\end{aligned}$$

  - Derivable w.r.t. τ, so can be solved using a gradient-based approach

Parametric vs. Non-Parametric Models

- Probabilistic linear regression and logistic regression are special cases of ***parametric models***, whose #parameters is fixed with respect to #data seen
  - $\hat{y} = \boldsymbol{w}^\top \boldsymbol{x}$ or $\hat{y} = \text{sign}(\boldsymbol{w}^\top \boldsymbol{x})$
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- Gaussian process, on the other hand, is a ***non-parametric model***
  - $\hat{\boldsymbol{y}}_M = \boldsymbol{K}_{M,N} \boldsymbol{K}_{N,N}^{-1} \boldsymbol{y}_N$, where each predicted label $\hat{y}$ is a linear combination of the labels in training set
  - ***Model complexity grows with*** N

Remarks

- Bayesian estimation:

$$\hat{\boldsymbol{y}} = \arg\max_{\boldsymbol{y}} \mathrm{P}(\boldsymbol{y} \,|\, \boldsymbol{x}, \mathbb{X}) = \arg\max_{\boldsymbol{y}} \int \mathrm{P}(\boldsymbol{y}, \Theta \,|\, \boldsymbol{x}, \mathbb{X}) d\Theta$$

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- Usually generalizes better given a small training set
- Unfortunately, solution may not be tractable in many applications
- Even tractable, incurs high computation cost
  - In GP, each batch of predictions $\hat{\boldsymbol{y}}_M = \boldsymbol{K}_{M,N} \boldsymbol{K}_{N,N}^{-1} \boldsymbol{y}_N$ may take $O(N^3)$ time
  - Not suitable for large-scale learning tasks

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